

Bayesian Model Uncertainty

STA721: Lecture 19

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Recap Diabetes Data

```

1 set.seed(8675309)
2 source("yX.diabetes.train.txt")
3 diabetes.train = as.data.frame(diabetes.train)
4 source("yX.diabetes.test.txt")
5 diabetes.test = as.data.frame(diabetes.test)
6 colnames(diabetes.test)[1] = "y"
7
8 str(diabetes.train)

```

```

'data.frame':   342 obs. of  65 variables:
 $ y      : num  -0.0147 -1.0005 -0.1444 0.6987 -0.2222 ...
 $ age    : num   0.7996 -0.0395 1.7913 -1.8703 0.113 ...
 $ sex    : num   1.064 -0.937 1.064 -0.937 -0.937 ...
 $ bmi    : num   1.296 -1.081 0.933 -0.243 -0.764 ...
 $ map    : num   0.459 -0.553 -0.119 -0.77 0.459 ...
 $ tc     : num  -0.9287 -0.1774 -0.9576 0.256 0.0826 ...
 $ ldl    : num  -0.731 -0.402 -0.718 0.525 0.328 ...
 $ hdl    : num  -0.911 1.563 -0.679 -0.757 0.171 ...
 $ tch    : num  -0.0544 -0.8294 -0.0544 0.7205 -0.0544 ...
 $ ltg    : num   0.4181 -1.4349 0.0601 0.4765 -0.6718 ...
 $ glu    : num  -0.371 -1.936 -0.545 -0.197 -0.979 ...

```



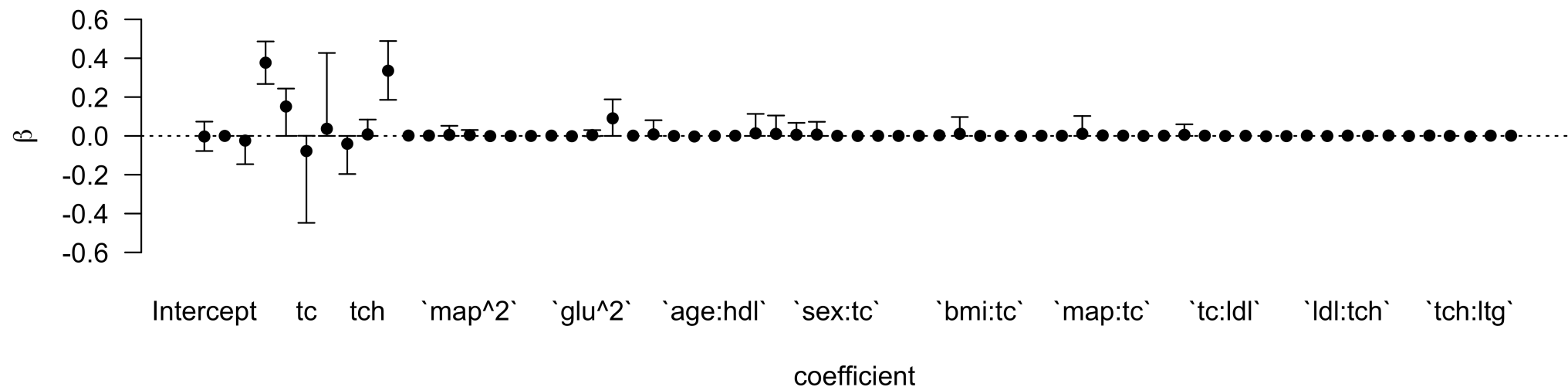
Credible Intervals under BMA

```

1 coef.diabetes = coefficients(diabetes.bas)
2 ci.coef.bas = confint(coef.diabetes, level=0.95)
3 plot(ci.coef.bas)

```

NULL



- uses Monte Carlo simulations from the posteriors of the coefficients
- uses HPD intervals from the CODA package to compute intervals



Out of Sample Prediction

- What is the optimal value to predict \mathbf{Y}^{test} given \mathbf{Y} under squared error?
- BMA is optimal prediction for squared error loss with Bayes

$$\mathbf{E}[\|\mathbf{Y}^{\text{test}} - a\|^2 \mid \mathbf{y}] = \mathbf{E}[\|\mathbf{Y}^{\text{test}} - \mathbf{E}[\mathbf{Y}^{\text{test}} \mid \mathbf{y}]\|^2 \mid \mathbf{y}] + \|\mathbf{E}[\mathbf{Y}^{\text{test}} \mid \mathbf{y}] - a\|^2$$

- Iterated expectations leads to BMA for $\mathbf{E}[\mathbf{Y}^{\text{test}} \mid \mathbf{Y}]$
- Prediction under model averaging

$$\hat{Y} = \sum_S (\hat{\alpha}_\gamma + \mathbf{X}_\gamma^{\text{test}} \hat{\beta}_\gamma) \hat{p}(\gamma \mid \mathbf{Y})$$

[1] 0.4556414



Credible Intervals & Coverage

- posterior predictive distribution

$$p(\mathbf{y}^{\text{test}} \mid \mathbf{y}) = \sum_{\gamma} p(\mathbf{y}^{\text{test}} \mid \mathbf{y}, \gamma) p(\gamma \mid \mathbf{y})$$

- integrate out α and β_{γ} to get a normal predictive given ϕ and γ (and \mathbf{y})
- integrate out ϕ to get a t distribution given γ and \mathbf{y}
- credible intervals via sampling
 - sample a model from $p(\gamma \mid \mathbf{y})$
 - conditional on a model sample $y \sim p(\mathbf{y}^{\text{test}} \mid \mathbf{y}, \gamma)$
 - compute HPD or quantiles from samples of y



95% Prediction intervals

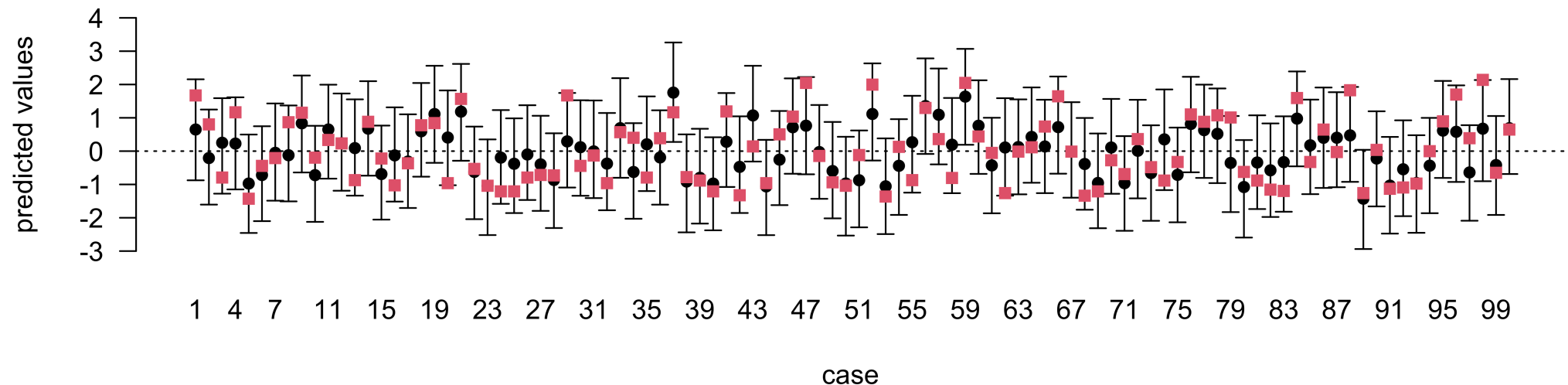
```
1 ci.bas = confint(pred.bas);  
2 coverage = mean(diabetes.test$y > ci.bas[,1] & diabetes.test$y <  
3 coverage
```

```
[1] 0.99
```

```
1 plot(ci.bas)
```

NULL

```
1 points(diabetes.test$y, col=2, pch=15)
```



Selection and Prediction

- BMA is optimal for squared error loss Bayes
- What if we want to use only a single model for prediction under squared error loss?
- HPM: Highest Posterior Probability model is optimal for selection, but not prediction
- MPM: Median Probability model (select model where $PIP > 0.5$) (optimal under certain conditions; nested models)
- BPM: Best Probability Model - Model closest to BMA under loss (usually includes more predictors than HPM or MPM)
- costs of using variables in prediction?



Example

```
1 pred.bas = predict(diabetes.bas,  
2                 newdata=diabetes.test,  
3                 estimator="BMA",  
4                 se=TRUE)  
5 mean((pred.bas$fit- diabetes.test$y)^2)
```

```
[1] 0.4556414
```

```
1 pred.bas = predict(diabetes.bas,  
2                 newdata=diabetes.test,  
3                 estimator="BPM",  
4                 se=TRUE)  
5 #MSE  
6 mean((pred.bas$fit- diabetes.test$y)^2)
```

```
[1] 0.4740667
```

```
1 #Coverage  
2 ci.bas = confint(pred.bas)  
3 mean(diabetes.test$y > ci.bas[,1] &  
4      diabetes.test$y < ci.bas[,2])
```

```
[1] 0.98
```



Theory - Consistency of g-priors

- desire that posterior probability of model goes to 1 as $n \rightarrow \infty$
 - does not always hold if the null model is true (may be highest posterior probability model)
 - need prior on g to depend on n (rules out EB and fixed g-priors with $g \neq n$)
 - asymptotically BMA collapses to the true model
- other quantities may converge i.e. posterior mean



Model Paradigms

- what if the true model γ_T is not in Γ ? What can we say?
- \mathcal{M} -complete; BMA converges to the model that is “closest” to the truth in Kullback-Leibler divergence
- \mathcal{M} -closed;
 - know $\gamma_T \notin \mathbf{G}$ so that $(p_\gamma) = 0 \forall \gamma \in \mathbf{G}$ but want to use models in \mathbf{G}
 - Predictive distribution $p(\mathbf{Y}^* | \mathbf{Y}, \gamma_T)$ is available
- \mathcal{M} -open;
 - know $\gamma_T \notin \mathbf{G}$ so that $(p_\gamma) = 0 \forall \gamma \in \mathbf{G}$ but want to use models in \mathbf{G}
 - Predictive distribution $p(\mathbf{Y}^* | \mathbf{Y}, \gamma_T)$ is not available. (too complicated to use, etc)



\mathcal{M} -Open and \mathcal{M} -Complete Prediction

Clyde & Iversen (2013) [pdf](#) motivate a solution via decision theory

- Use the models in \mathbf{G} to predict \mathbf{Y}^* given \mathbf{Y} under squared error loss

$$E[\mathbf{Y}^*, \sum_{\gamma \in \mathbf{G}} \omega_{\gamma} \hat{\mathbf{Y}}_{\gamma}^* \mid \mathbf{Y}] = \int (\mathbf{Y}^* - \sum_{\gamma \in \mathbf{G}} \omega_{\gamma} \hat{\mathbf{Y}}_{\gamma}^*)^2 p(\mathbf{Y}^* \mid \mathbf{Y})$$

- Still use a weighted sum of predictions or densities from models in \mathbf{G} but now the weights are not probabilities but are chosen to minimize the loss function
 - uses additional constraints of penalties on the weights as part of the loss function
 - need to approximate the predictive distribution for $\mathbf{Y}^* \mid \mathbf{Y}$ (via an approximate Dirichlet Process Model)
 - latter is related to “stacking” (Wolpert 1972) which is a frequentist method of ensemble learning using cross-validation;



Summary

- Choice of prior on β_γ
 - multivariate Spike & Slab
 - products of independent Spike & Slab priors
 - intermediates block g-priors
 - non-semi-conjugate
 - non-local priors
 - shrinkage priors without point-masses
- priors on the models (sensitivity)
- computation (MCMC, “stochastic search”, adaptive MH, variational, orthogonal data augmentation, reversible jump-MCMC)
- decision theory - select a model or “average” over all models
- asymptotic properties - large n and large $p > n$



Other aspects of model selection?

- transformations of \mathbf{Y}
- functions of \mathbf{X} : interactions or nonlinear functions such as splines kernels
- choice of error distribution
- outliers

