

# Transformations and Normality Assumptions

STA 721: Lecture 22

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# Outline

- Normality & Transformations
- Box-Cox
- Variance Stabilizing Transformations
- Nonlinear Regression

Readings: Christensen Chapter 13, Seber & Lee Chapter 10 & Wakefield Chapter 6



# Model Assumptions

Linear Model:

$$\mathbf{Y} = \boldsymbol{\mu} + \boldsymbol{\epsilon}$$

Assumptions:

$$\begin{aligned}\boldsymbol{\mu} \in C(\mathbf{X}) &\Leftrightarrow \boldsymbol{\mu} = \mathbf{X}\boldsymbol{\beta} \\ \boldsymbol{\epsilon} &\sim \mathbf{N}(\mathbf{0}_n, \sigma^2 \mathbf{I}_n)\end{aligned}$$

- Normal Distribution for  $\mathbf{Y}$  with constant variance or fixed covariance
- linearity of  $\boldsymbol{\mu}$  in  $\mathbf{X}$
- Computational Advantages of Normal Models
- Robustify with heavy tailed error distributions



# Checking via QQ-Plots

- QQ-Plots are a graphical tool to assess normality
- Order residuals  $e_i: e_{(1)} \leq e_{(2)} \dots \leq e_{(n)}$  sample order statistics or sample quantiles (standardized - divide by  $\sqrt{1 - h_{ii}}$ )
- Let  $z_{(1)} \leq z_{(2)} \dots z_{(n)}$  denote the expected order statistics of a sample of size  $n$  from a standard normal distribution “theoretical quantiles”
- If the  $e_i$  are normal then  $\mathbf{E}[e_{(i)} / \sqrt{1 - h_{ii}}] = \sigma z_{(i)}$
- Expect that points in a scatter plot of  $e_{(i)} / \sqrt{1 - h_{ii}}$  and  $z_{(i)}$  should be on a straight line.
- Judgment call - use simulations to gain experience!



# Animal Example

```
1 data(Animals, package="MASS")  
2 plot(brain ~ body, data=Animals, xlab="Body Weight (kg)", ylab="Brain We
```

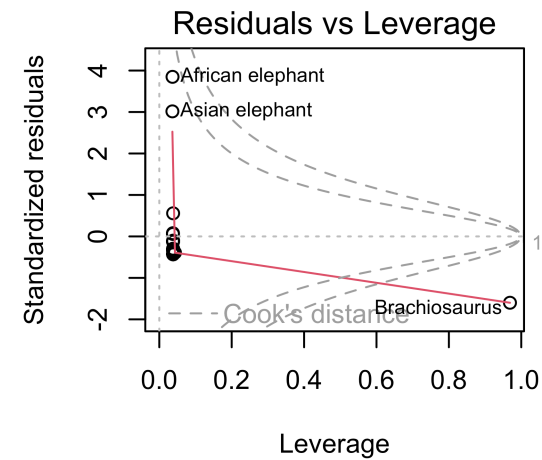
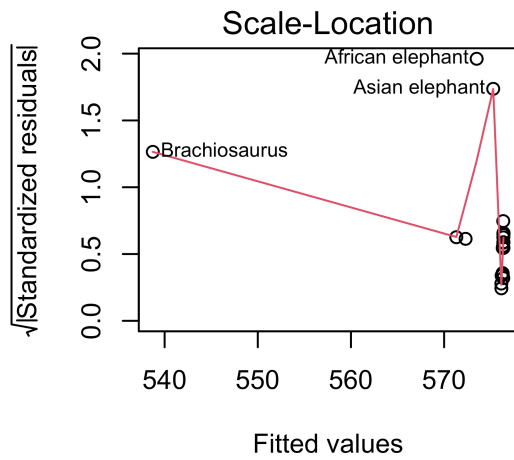
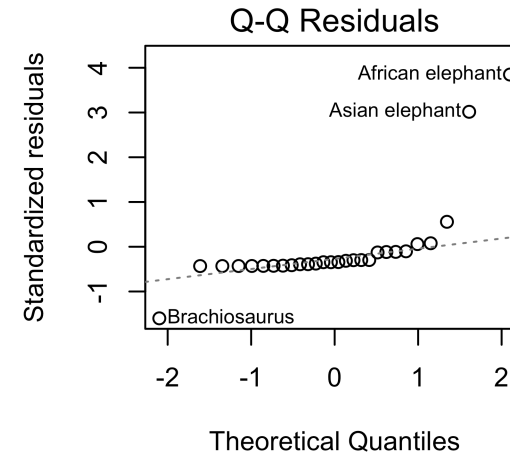
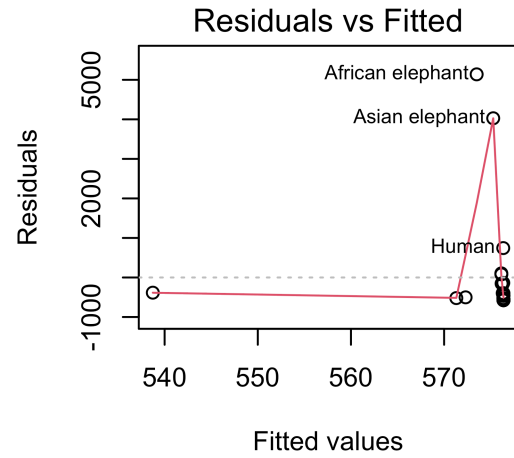




# Residual Plots

```
1 brains.lm <- lm(brain ~ body, data=Animals)
2 par(mfrow=c(2,2))
3 plot(brains.lm)
```







# Normality Assumption

Recall:

$$\begin{aligned}\mathbf{e} &= (\mathbf{I} - \mathbf{P}_{\mathbf{X}})\mathbf{Y} \\ &= (\mathbf{I} - \mathbf{P}_{\mathbf{X}})(\mathbf{X}\hat{\boldsymbol{\beta}} + \boldsymbol{\epsilon}) \\ &= (\mathbf{I} - \mathbf{P}_{\mathbf{X}})\boldsymbol{\epsilon}\end{aligned}$$

$$e_i = \epsilon_i - \sum_{j=1}^n h_{ij}\epsilon_j$$

- Lyapunov CLT (independent but not identically distributed) implies that residuals will be approximately normal (even for modest  $n$ ), if the errors are not normal
- *Supernormality of residuals*
- clearly not the case here!



# Box-Cox Transformation

Box and Cox (1964) suggested a family of power transformations for  $Y > 0$

$$U(\mathbf{Y}, \lambda) = Y^{(\lambda)} = \begin{cases} \frac{(Y^\lambda - 1)}{\lambda} & \lambda \neq 0 \\ \log(Y) & \lambda = 0 \end{cases}$$

- Estimate  $\lambda$  by maximum Likelihood

$$\mathcal{L}(\lambda, \boldsymbol{\beta}, \sigma^2) \propto \prod f(y_i | \lambda, \boldsymbol{\beta}, \sigma^2)$$

- $U(\mathbf{Y}, \lambda) = Y^{(\lambda)} \sim \mathbf{N}(\mathbf{X}\boldsymbol{\beta}, \sigma^2)$
- Jacobian term is  $\prod_i y_i^{\lambda-1}$  for all  $\lambda$
- Profile Likelihood based on substituting MLE  $\boldsymbol{\beta}$  and  $\sigma^2$  for each value of  $\lambda$  is

$$\log(\mathcal{L}(\lambda)) \propto (\lambda - 1) \sum_i \log(Y_i) - \frac{n}{2} \log(\text{SSE}(\lambda))$$

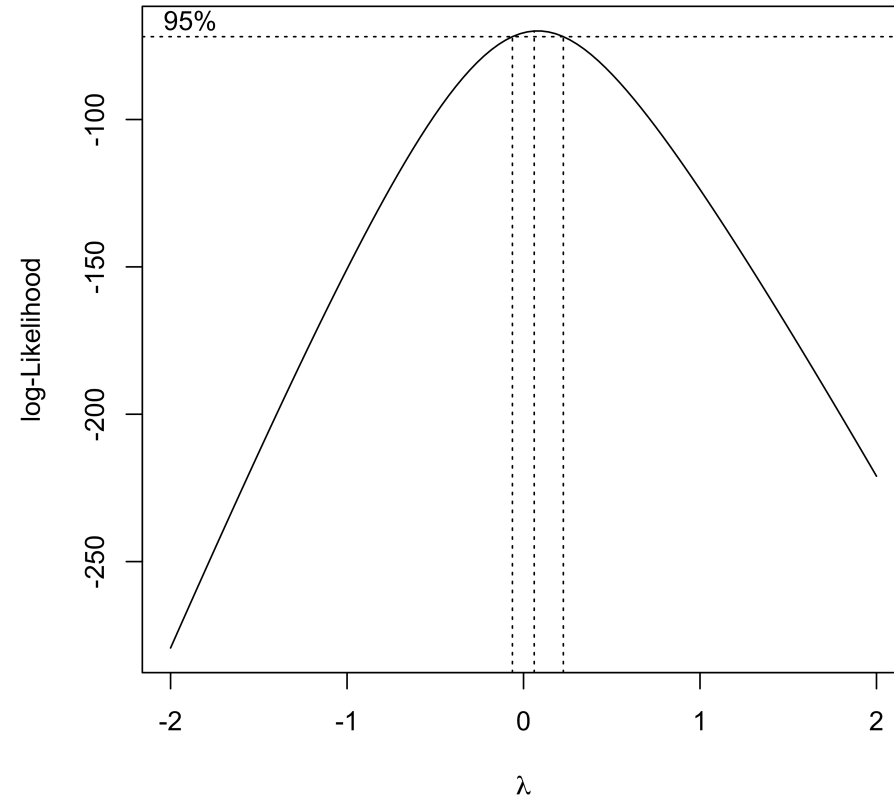


# Profile Likelihood

- Profile Likelihood is a function of  $\lambda$  obtained by substituting the MLE of  $\beta$  and  $\sigma^2$  for each value of  $\lambda$

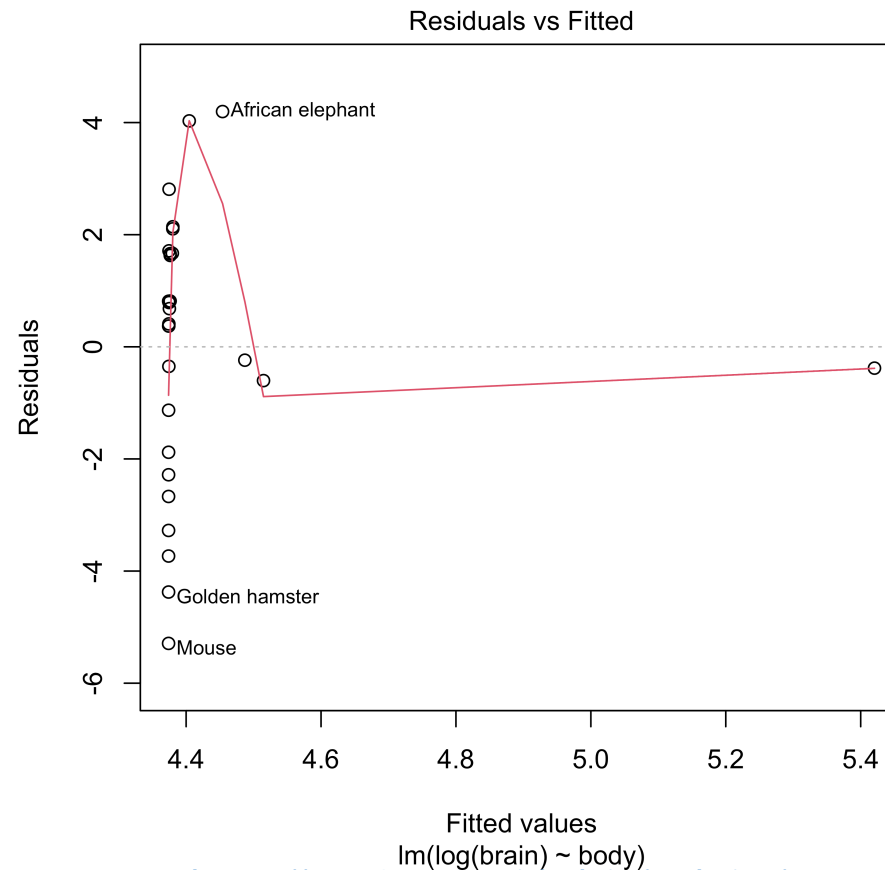
```
1 MASS::boxcox(brains.lm, lambda=seq(-2, 2, by=0.1))
```





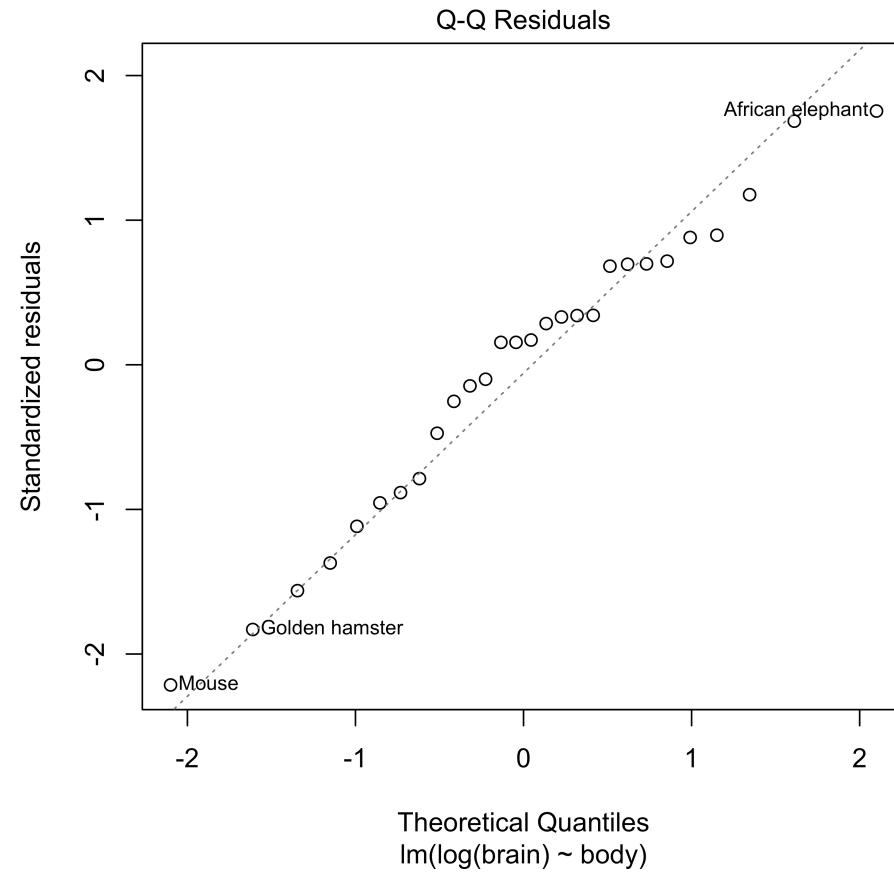
# Residuals after Transformation of Response

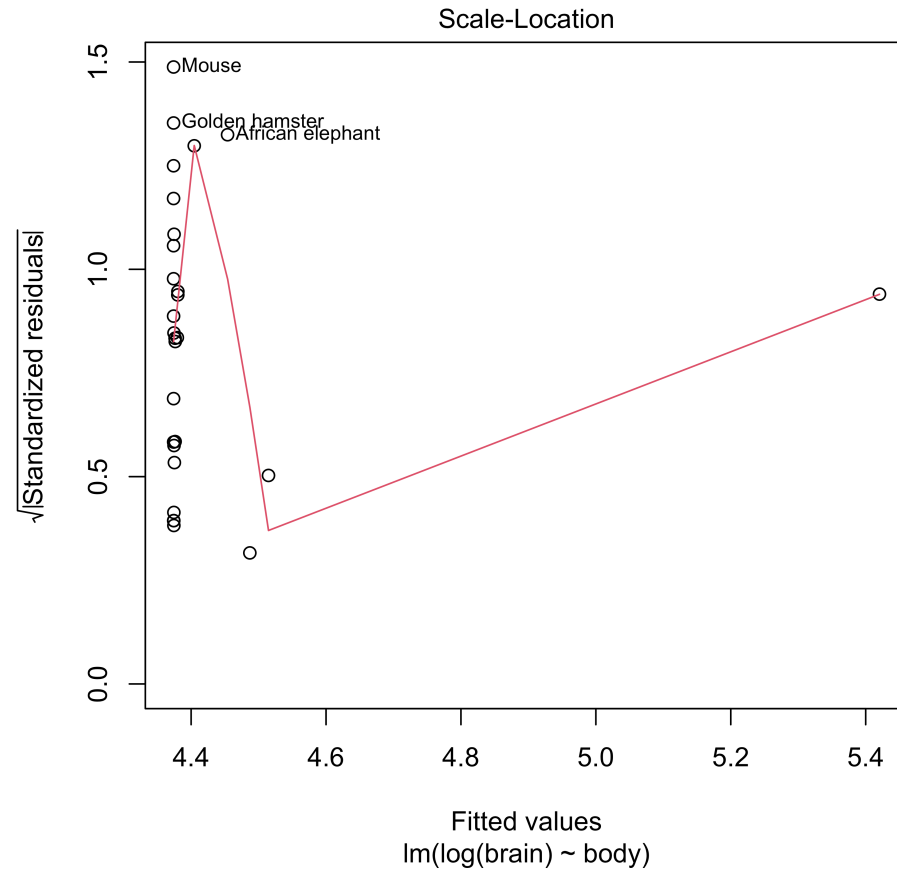
```
1 plot(lm(log(brain) ~ body, data=Animals))
```



<https://sta721-F24.github.io/website/>





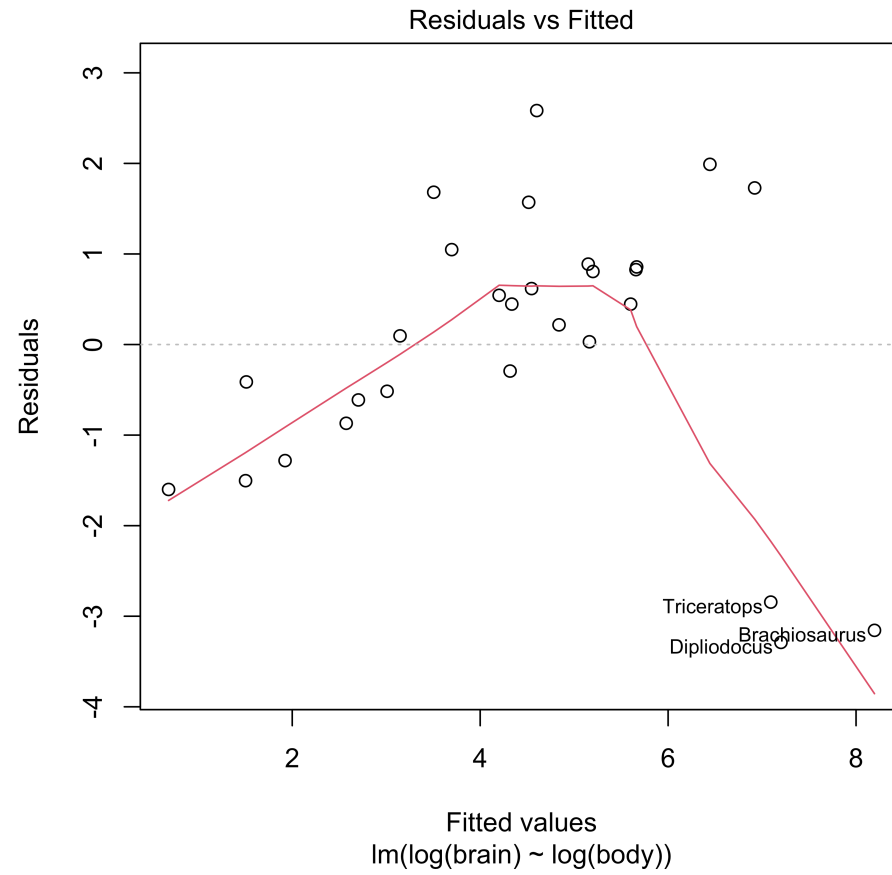


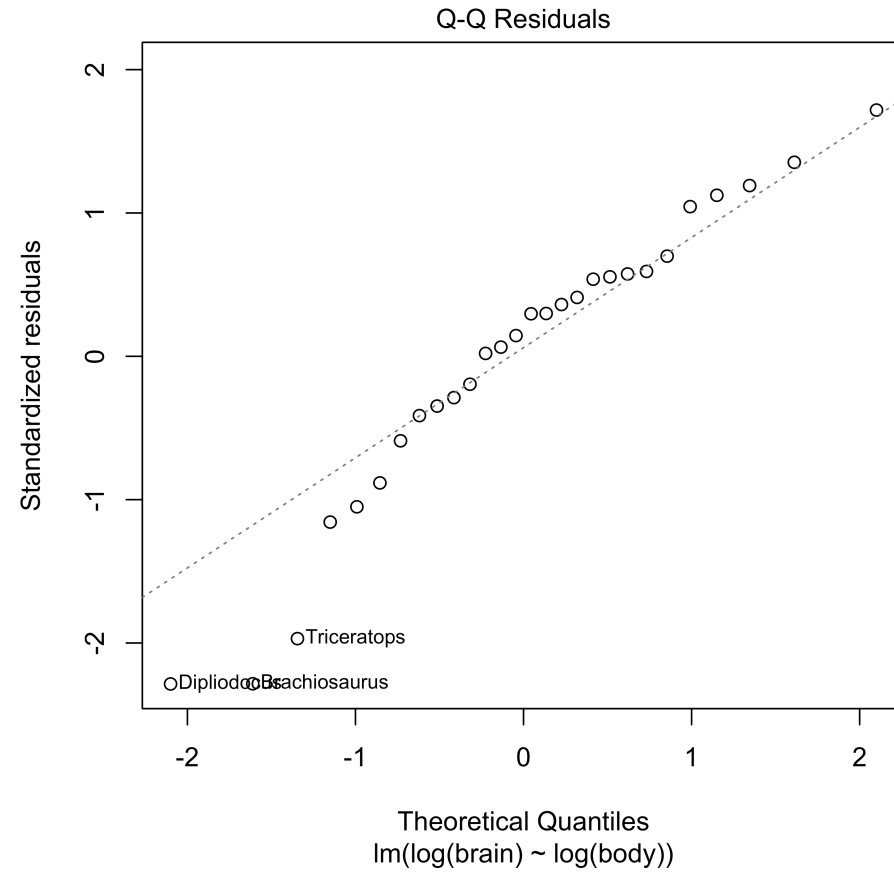
# Residuals after Transformation of Response and Predictor

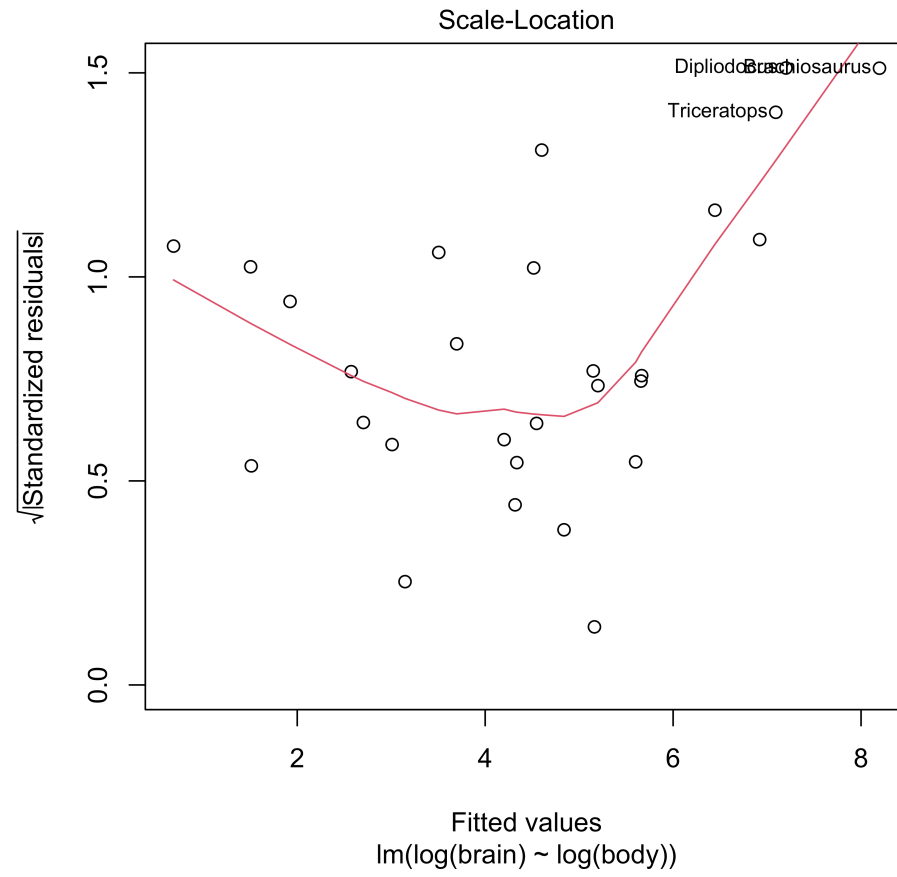
```
1 logbrain.lm <- lm(log(brain) ~ log(body), data=Animals)
2 plot(logbrain.lm)
```





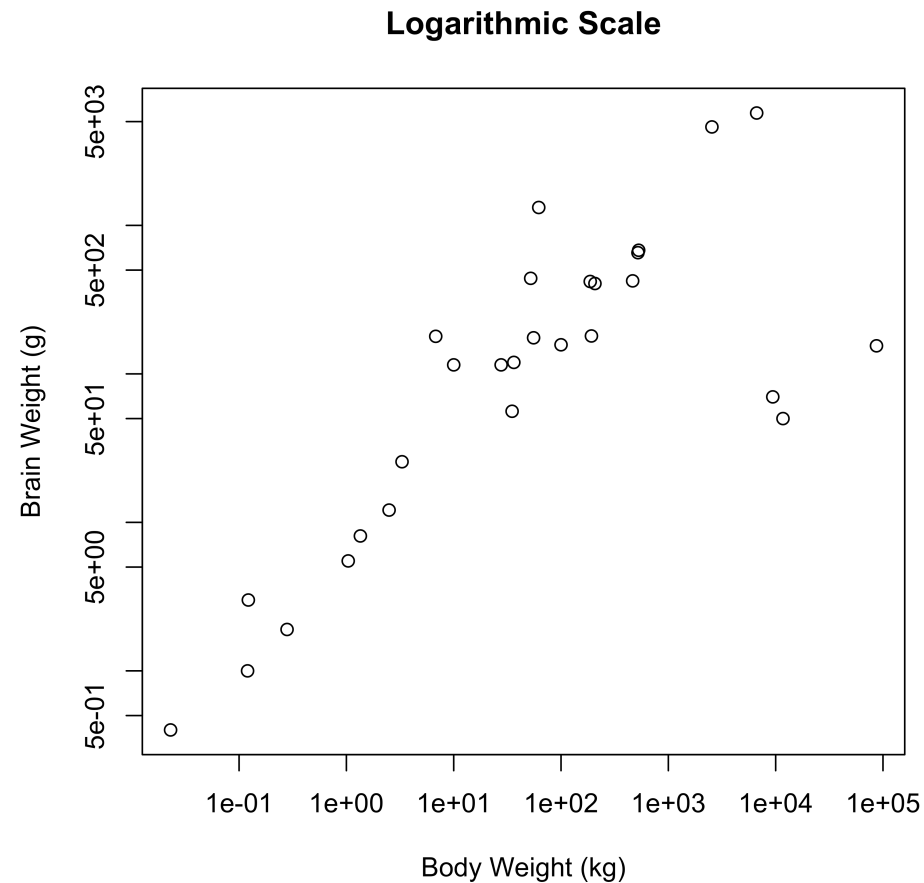






# Transformed Data

```
1 plot(brain ~ body, data=Animals, xlab="Body Weight (kg)", ylab="Brain We
```



# Test that Dinosaurs are from a Different Population (outliers)

```

1 logbrains.nodino.lm = lm(log(brain) ~ log(body) +
2                       I(row.names(Animals) == "Triceratops") +
3                       I(row.names(Animals) == "Brachiosaurus") +
4                       I(row.names(Animals) == "Dipliodocus"),
5                       data=Animals)
6
7 anova(logbrain.lm, logbrains.nodino.lm)

```

## Analysis of Variance Table

Model 1:  $\log(\text{brain}) \sim \log(\text{body})$

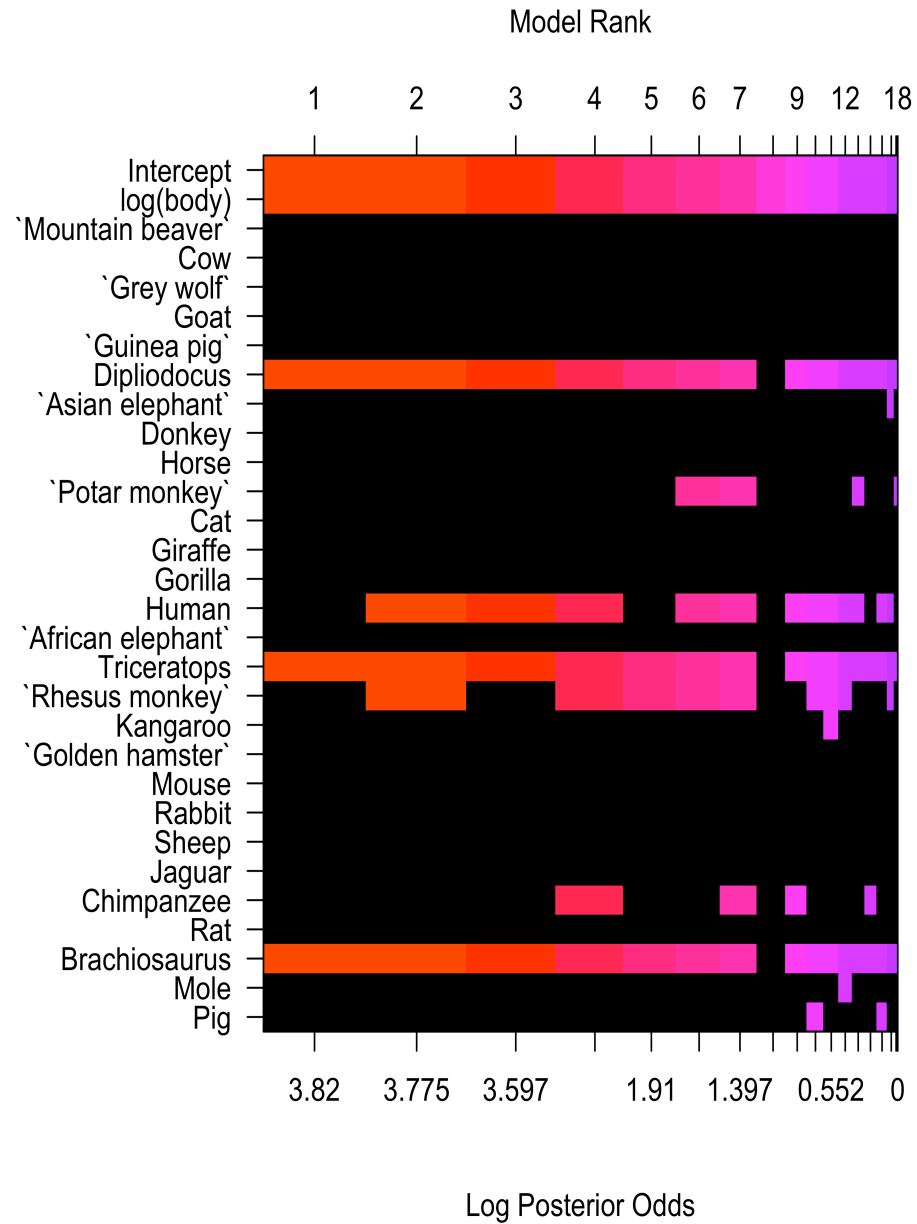
Model 2:  $\log(\text{brain}) \sim \log(\text{body}) + I(\text{row.names}(\text{Animals}) == \text{"Triceratops"}) + I(\text{row.names}(\text{Animals}) == \text{"Brachiosaurus"}) + I(\text{row.names}(\text{Animals}) == \text{"Dipliodocus"})$

	Res.Df	RSS	Df	Sum of Sq	F	Pr(>F)
1	26	60.988				
2	23	12.117	3	48.871	30.92	3.031e-08



```
1 Animals = cbind(Animals, diag(28)); colnames(Animals)[3:30] = rownames(Animals)
2 brains.bas = bas.lm(log(brain) ~ log(body) + . - body, data=Animals,
3                   prior="hyper-g-n", a=3, modelprior=beta.binomial(1,28))
4 image(brains.bas, rotate=FALSE)
```





# Variance Stabilizing Transformations

- If  $Y - \mu$  (approximately)  $N(0, h(\mu))$
- Delta Method implies that

$$g(Y) \sim N(g(\mu), g'(\mu)^2 h(\mu))$$

- Find function  $g$  such that  $g'(\mu)^2 / h(\mu)$  is constant

$$g(Y) \sim N(g(\mu), c)$$

- Poisson Counts (need  $Y > 3$ ),  $g$  is the square root transformation
- Binomial:  $\arcsin(\sqrt{Y})$

Note: transformation for normality may not be the same as the variance stabilizing transformation; boxcox assumes mean function is correct

Generalized Linear Models are preferable to transforming data, but may still be useful for starting values for MCMC





# Nonlinear Regression

- Drug concentration of caldralazine at time  $X_i$  in a cardiac failure patient given a single 30mg dose ( $D = 30$ ) given by

$$\mu(\boldsymbol{\beta}) = \left[ \frac{D}{V} \exp(-\kappa_e x_i) \right]$$

with  $\boldsymbol{\beta} = (V, \kappa_e)$   $V = volume$  and  $\kappa_e$  is the elimination rate

- If  $Y_i = \left[ \frac{D}{V} \exp(-\kappa_e x_i) \right] \times \epsilon_i$  with  $\log(\epsilon_i) \stackrel{\text{iid}}{\sim} N(0, \sigma^2)$  then the model is *intrinsically* linear (can transform to linear model)

$$\log(\mu(\boldsymbol{\beta})) = \log \left[ \frac{D}{V} \exp(-\kappa_e x_i) \right] = \log[D] - \log(V) - \kappa_e x_i$$

$$\log(Y_i) - \log[30] = \beta_0 + \beta_1 x_i + \epsilon_i$$

where  $\epsilon_i$  has a log normal distribution



# Nonlinear Least Squares Example

```

1 x = c(2,4,6,8,10,24,28, 32)
2 y = c(1.63, 1.01, .73, .55, .41,
3
4 conc.lm = lm(I(log(y) - log(30))
5
6 vhat = exp(-coef(conc.lm)[1])
7 khat = -coef(conc.lm)[2]
8
9 vhat

```

(Intercept)  
16.66331

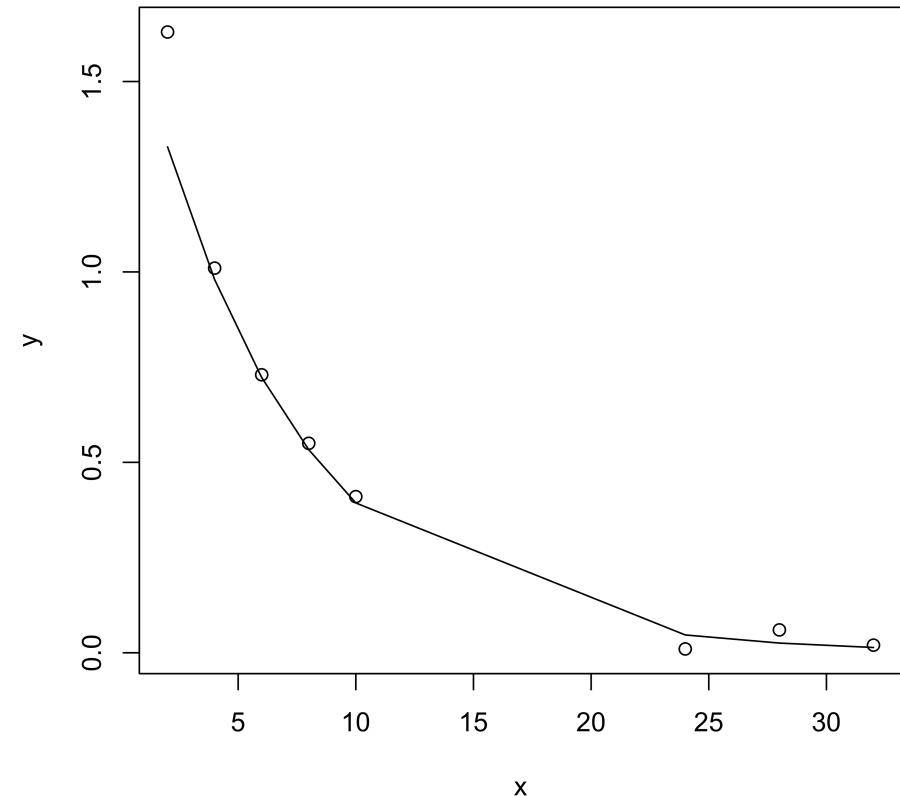
```
1 khat
```

x  
0.1521064

```

1 plot(x, y)
2 lines(x, (30/vhat)*exp(-khat*x))

```



# Additive Error Model

- If  $\mathbf{Y} = \left[ \frac{D}{V} \exp(-\kappa_e x_i) \right] + \epsilon_i$  model is intrinsically nonlinear and cannot transform to a linear model.
- need to use nonlinear least squares to estimate  $\beta$  and  $\sigma^2$
- or MCMC to estimate the posterior distribution of  $\beta$  and  $\sigma^2$



# Intrinsically Linear Model nls

```
1 df = data.frame(y=y, x=x)
2 logconc.nlm = nls( log(y) ~ log((30/V)*exp(-k*x)), data=df, start=list(V=
3 summary(logconc.nlm)
```

Formula:  $\log(y) \sim \log((30/V) * \exp(-k * x))$

Parameters:

	Estimate	Std. Error	t value	Pr(> t )
V.(Intercept)	16.66331	7.11923	2.341	0.057796
k.x	0.15211	0.02368	6.423	0.000673

Residual standard error: 0.7411 on 6 degrees of freedom

Number of iterations to convergence: 0

Achieved convergence tolerance: 4.056e-09



# Intrinsically Nonlinear Model

Formula:  $y \sim (30/V) * \exp(-k * x)$

Parameters:

	Estimate	Std. Error	t value	Pr(> t )
V	13.06506	0.60899	21.45	6.69e-07
k	0.18572	0.01124	16.52	3.14e-06

Residual standard error: 0.05126 on 6 degrees of freedom

Number of iterations to convergence: 4

Achieved convergence tolerance: 7.698e-06



# Functions of Interest

Interest is in

- clearance:  $V\kappa_e$
- elimination half-life  $x_{1/2} = \log 2 / \kappa_e$
- Use properties of MLEs: asymptotically  $\hat{\beta} \sim N\left(\beta, I(\hat{\beta})^{-1}\right)$
- Asymptotic Distributions
- Bayes obtain the posterior directly for parameters and functions of parameters!
  - Priors?
  - Constraints on Distributions?
  - Bayes Factor for testing normal vs log-normal models?



# Summary

- Optimal transformation for normality (MLE) depends on choice of mean function
- May not be the same as the variance stabilizing transformation
- Nonlinear Models as suggested by Theory or Generalized Linear Models are alternatives
- “normal” estimates may be useful approximations for large  $p$  or for starting values for more complex models (where convergence may be sensitive to starting values)

